

Robotics in Environmental Site Assessment

Sixth International Symposium on Bioremediation and Sustainable Remediation Technologies

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Austin, Texas

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Agenda for Robotics in Environmental Site Assessment

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Background

Perspective of Presentation



Application

Excavation Monitoring



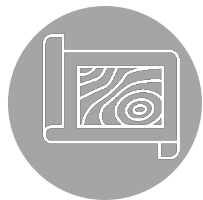
Case Study

Robotics in Environmental Industry



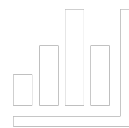
Limitations

Areas of Learning and Improvement



Application

Surface Soil Delineation



Going Forward

Current and Future Application

Background

- Robots Tested
 - Remote and autonomous ground robots
- Part of a larger research effort
 - Chevron Technical Center
 - Trihydro Corporation
 - Carnegie Mellon University
 - HEBI Robotics
- Perspective of an end user
- Many potential uses, but will focus on environmental application



Background

- Robotics Applications in the Environmental Industry
 - Unsafe Work Environment
 - Hazardous Atmosphere
 - Hard to Access Spaces
 - Advantages in Comparison to Human
 - Data processing
 - Repetitive tasks
 - Terrestrial and aquatic



Applications/Case Studies

- Surface Soil Delineation
 - Land Treatment Unit (LTU) adjacent to former refinery in Midwest U.S.
 - Use of controlled and autonomous vehicle to delineate lead concentrations in surface soil
- Excavation Monitoring
 - Former oil fields in central coast of California, U.S.
 - Use of controlled vehicle to retrieve soil sample to keep worker from hazardous areas



Image 1: Robot at LTU in Midwest U.S.



Image 2: Robot at Excavation Pit in California, U.S.

Surface Soil Delineation

- **Site Background**

- LTU for treatment of petroleum waste
- Dense honeysuckle forest present mobility issues



Image 1: LTU Forest



Image 2: Former Refinery and LTU, Google Earth

Surface Soil Delineation

- Human Health Risk Assessment
 - Identified lead (Pb) as a potential risk-driver
 - Potential remediation includes delineation and excavation of soil above lead cleanup goal
 - Elevated lead concentration identified in northern section of LTU
 - This area selected for robotics test

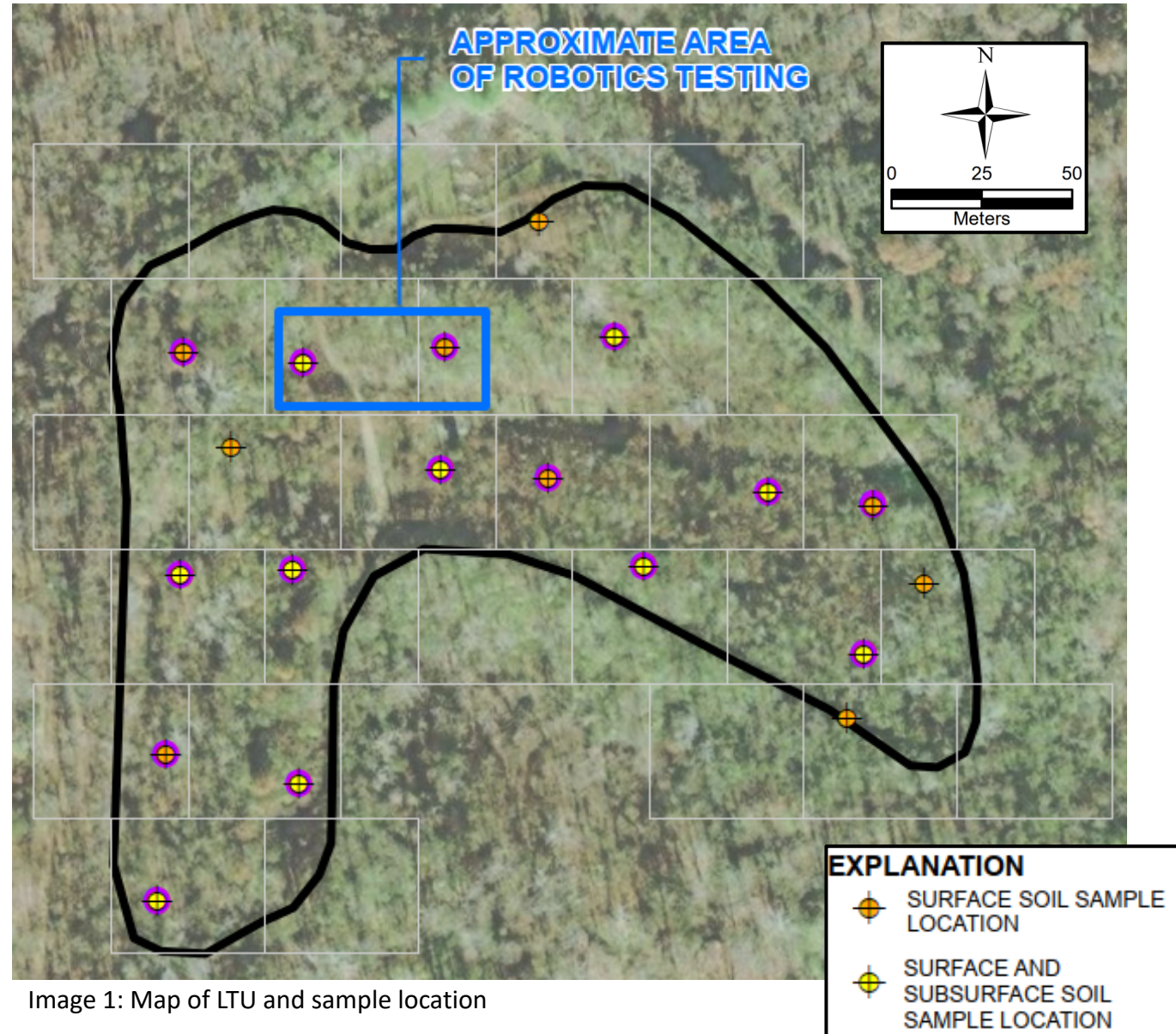


Image 1: Map of LTU and sample location

Surface Soil Delineation

- Robotics delineation technique
 - Define sampling area
 - Screen surface soils
 - Sample location selected by dynamic algorithm
 - Areas with elevated lead concentration
 - Areas with unknown lead concentration
 - Use LiDAR to avoid obstructions
 - Return a contoured map of lead (Pb) concentration

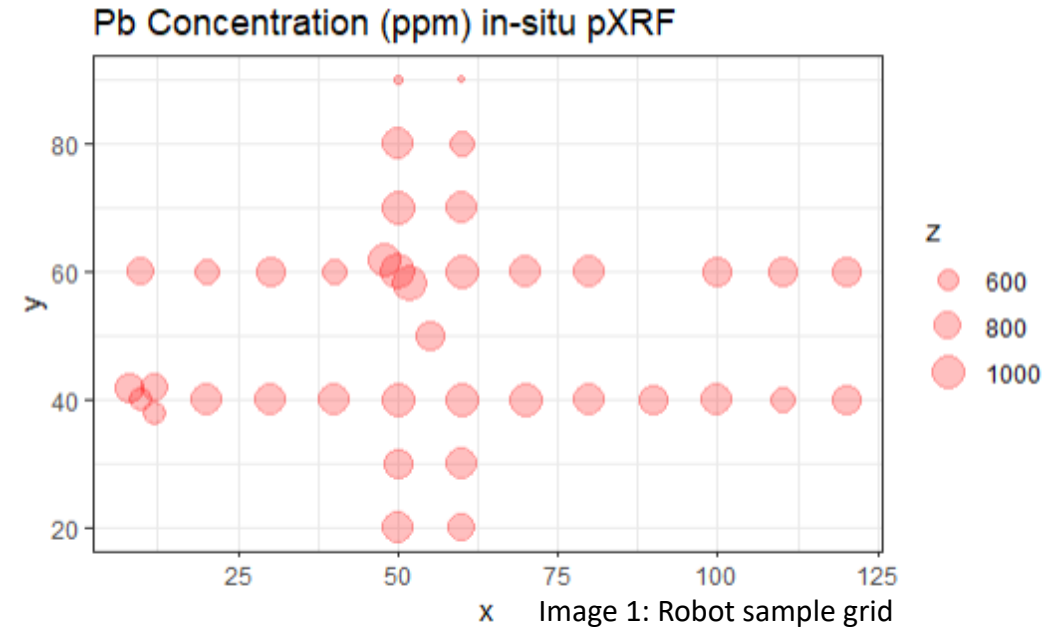


Image 2: Robot generated lead contour map

Surface Soil Delineation

- Typical Soil Delineation and Removal
 - Adjacent former tank farm soil delineation and “hot-spot” removal
 - Stepwise sampling and analysis
 - Cost and time can be unknown
 - Additional expenses could be avoided
- Worker safety
 - Entering excavation
 - Working around heavy equipment
 - Contaminants in soil



Surface Soil Delineation

- Typical Soil Delineation and Removal
 - 1300 square meters (m²) estimated but 2000 m² soil removed
 - 800 cubic meters (m³) estimated but 1200 soil removed
 - 32 total delineation samples and 9 confirmatory samples
 - 7 delineation sampling events with minimum of 14 weeks sampling

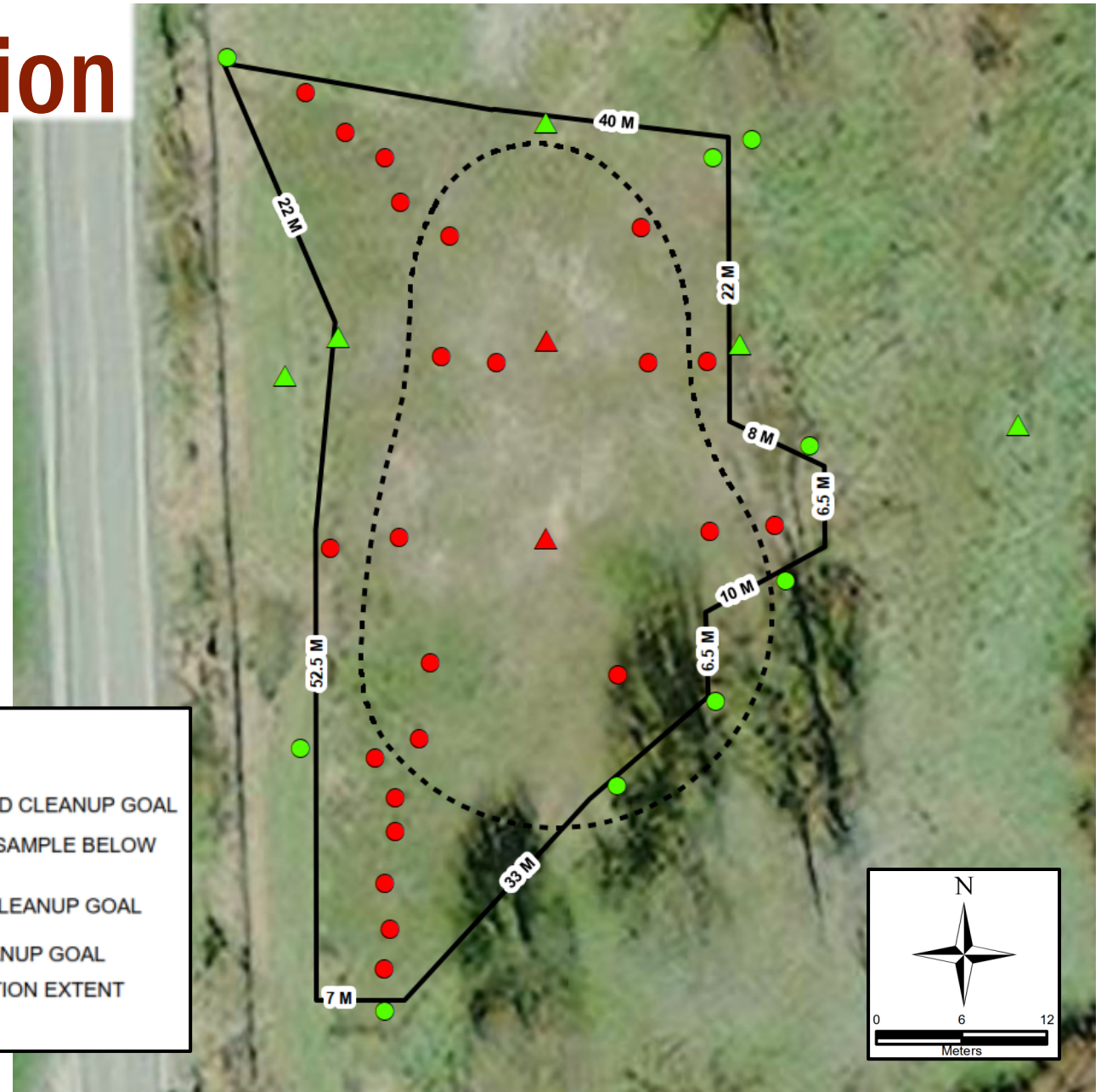
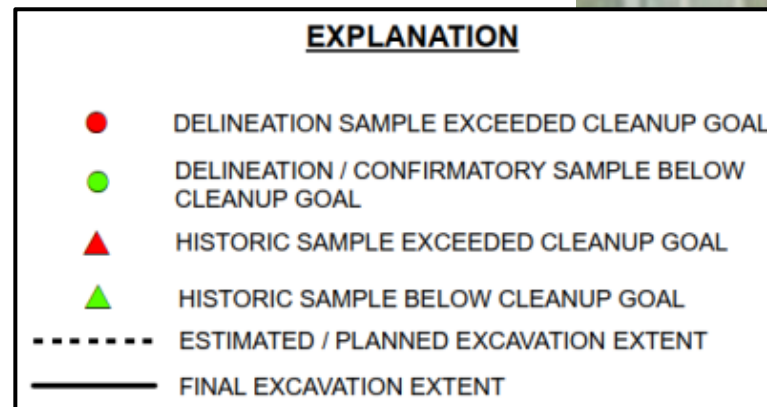


Image 1: Area of Former Tank Farm Excavation

Surface Soil Delineation

- Typical Soil Delineation and Removal

- Delineation of 2000 m² area cost approximately \$9.5k vs robot assisted at \$3.5k, excluding all costs associated with both methods
 - 65% cost reduction potential becomes more significant for larger excavations
- Waste disposal cost approximately \$120k vs estimate of \$75k

Description	Unit Cost	Units	Existing Delineation an Excavation Method		Robotic Assisted with Dynamic Algorithm Excavation	
			Quantity	Cost	Quantity	Cost
Technician-Hours	\$ 85.00	Hour	78	\$ 6,630.00	20	\$ 1,700.00
Robot Operator-Hours	\$ 125.00	Hour	--	--	8	\$ 1,000.00
Total Travel Days	\$ 75.00	Day	7	\$ 525.00	1	\$ 75.00
Analytical Sample	\$ 72.00	Sample	32	\$ 2,304.00	9	\$ 648.00
Total Cost				\$ 9,459.00		\$ 3,423.00

Table 1: Cost Comparison

Excavation Monitoring

- Former Oil Fields in Central Coast California
- Loose Dune Sand Terrain
- Petroleum Hydrocarbon (TPH) Impacted Soils
- Worker Safety Considerations
 - Excavation wall collapse
 - Heavy equipment
 - Contaminant exposure



Image 1: Photo of Excavation and Stockpile

Excavation Monitoring

- Typical Soil Excavation
 - Former well pads
 - Former recovery sumps
 - Petroleum impacted surface source
- Excavation Oversight
 - Determine Extent of excavation based on visual, physical, and analytical methods
 - Safely collect analytical samples to confirm extent of excavation
 - Typical sample locations from middle and four edges of excavation

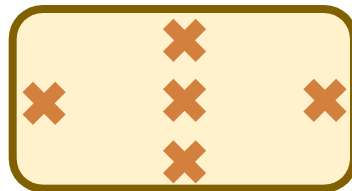


Figure 1: Excavation Sample Schematic



Image 1: Photo of Typical Soil Excavation

Excavation Monitoring

- Robotics Assisted Excavation Monitoring
 - Use remote or autonomous controls to locate excavation sample location
 - Homogenize soils with auger at sample location
 - Use sensor to measure soil moisture content
 - Use infrared (IR) meter to measure TPH concentration
 - Track surface level carbon dioxide (CO₂) for qualitative biodegradation indicator



Image 1: Photo of Robot Used for Excavation Monitoring



Image 2: Example observation view from field tablet



Limitations

- **Primary Limitations**

- Mobility challenges
- Field meter restriction
- Sample depth and screening technique

- **Practicality Limitations**

- Capital cost
- Robot operation and assembly currently requires trained human support
- Human currently better suited for many environmental assessment applications



Image 1-3: Photos of Robots

Summary and Next Steps

- **Robots should become important future resource for environmental practitioners**
 - Can be used in environmental site assessment to reduce labor cost while keeping workers out of harm's way
- **Overcoming Limitations**
 - Test robot with different terrain and objectives
 - Engineer sampling device and instrumentation
 - Work with multi-disciplinary project team to further explore site assessment application



Image 1: Photo of Robot

QUESTIONS / DISCUSSION

WHAT

WHY

WHERE

WHEN

WHO

HOW

